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Introduction

- **Trajectory-Based Operations (TBO)** will require new onboard avionics (e.g. Cockpit Display of Traffic Information, CDTI) to provide pilots with necessary information about surrounding traffic and terrain
 - There are several constraints on the use and implementation of the CDTI in the near future:
 - Limited space in the cockpit
 - Instability of the cockpit
 - Input method
- **Force-feedback** has been proposed as a way of improving performance in HCI tasks that have a high degree of difficulty (Griffiths and Gillespie, 2005)
 - Force-feedback works by either assisting or resisting operator movement
 - The use of an attractive force basin (or virtual fixture) has been found to decrease target selection time by 20-25% (e.g. Eberhardt, Neverov, West, and Sanders, 1997; Hassler and Goldenberg, 1998)
- **Movement direction** (relative to the starting position) is also important to evaluate, since the CDTI will accommodate a wide range of movement
- Fitts' law research has largely investigated one-dimensional movements, with some exception:
 - MacKenzie and Buxton (1992) and Whisenand and Emurian (1996) noted that movements with a computer mouse along the horizontal and vertical axes resulted in faster movements than those along diagonal axes.
- **Relevance to NASA** – study used force feedback to determine potential benefits in operator performance with the Cockpit Situated Display (CSD)
 - CSD was developed by the Flight Deck Display Research Center (FDDRL) at NASA Ames

Purpose

- This study examined the effect of force-feedback in a Fitts' law task using a variety of movement directions
 - It also utilized a task environment that roughly mirrored a future flight deck environment:
 - Small display size
 - Small and closely spaced icons

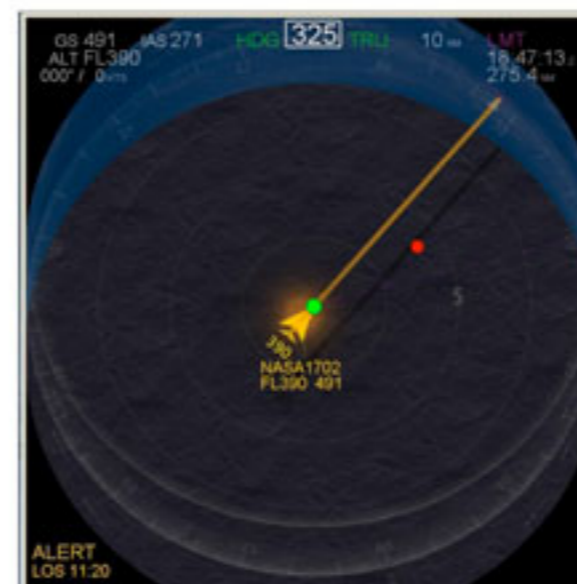
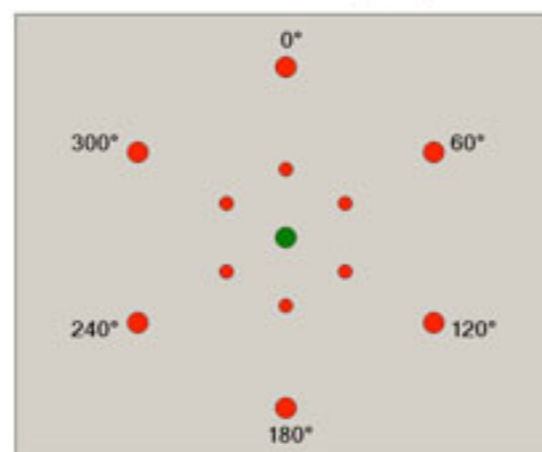
Method

- **Subjects**
 - 12 students from CSULB; paid \$10/hr for 6 hrs of participation
- **Apparatus**
 - Standard Logitech laser mouse
 - Novint Falcon input device
 - 4" x 4" x 4" operational workspace
 - Programmed to provide force feedback using modified Newton's gravitational law equation



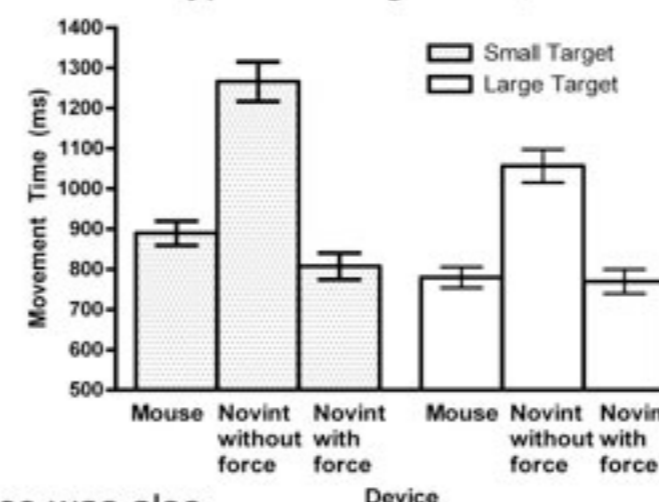
Method

- **Procedure**
 - Start and target icons displayed over screen shot of an active CDTI display, with no traffic (shown below)
 - Start icon remained constant size (1/4") and location (center)
 - Target position and size varied randomly from trial to trial
 - 8 blocks per device condition, 120 trials per block
 - **IV's:**
 - *Device Type* - mouse, Novint with Force, Novint without Force
 - *Target Size* - 1/6" or 1/4"
 - *Target Distance* - 5/6" or 2 1/2"
 - *Target Angle* - 0°, 60°, 120°, 180°, 240°, and 300°
 - **DV:** movement time (ms)

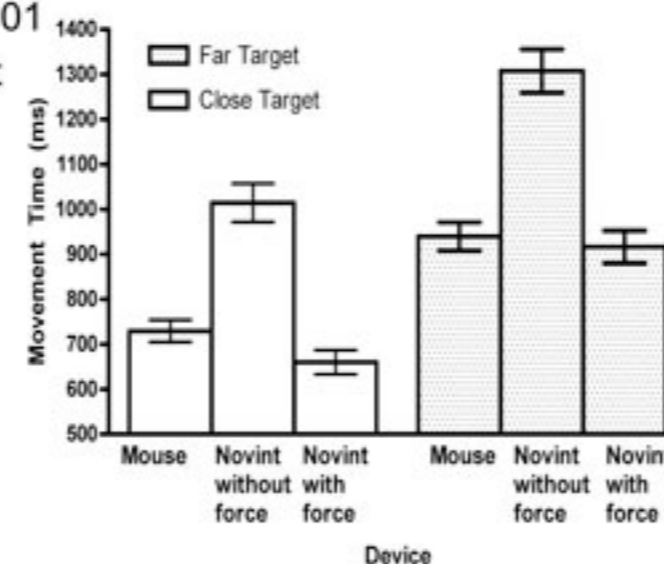


Results

- **Target Size:**
 - Main effect of target size, $F(1, 11) = 386.68, p < .001$
 - Significantly longer to select small target
 - Significant interaction between device type and target size, $F(2, 22) = 204.82, p < .001$
 - Novint with Force was quicker than Mouse when selecting the small target size **only** ($p < .01$)

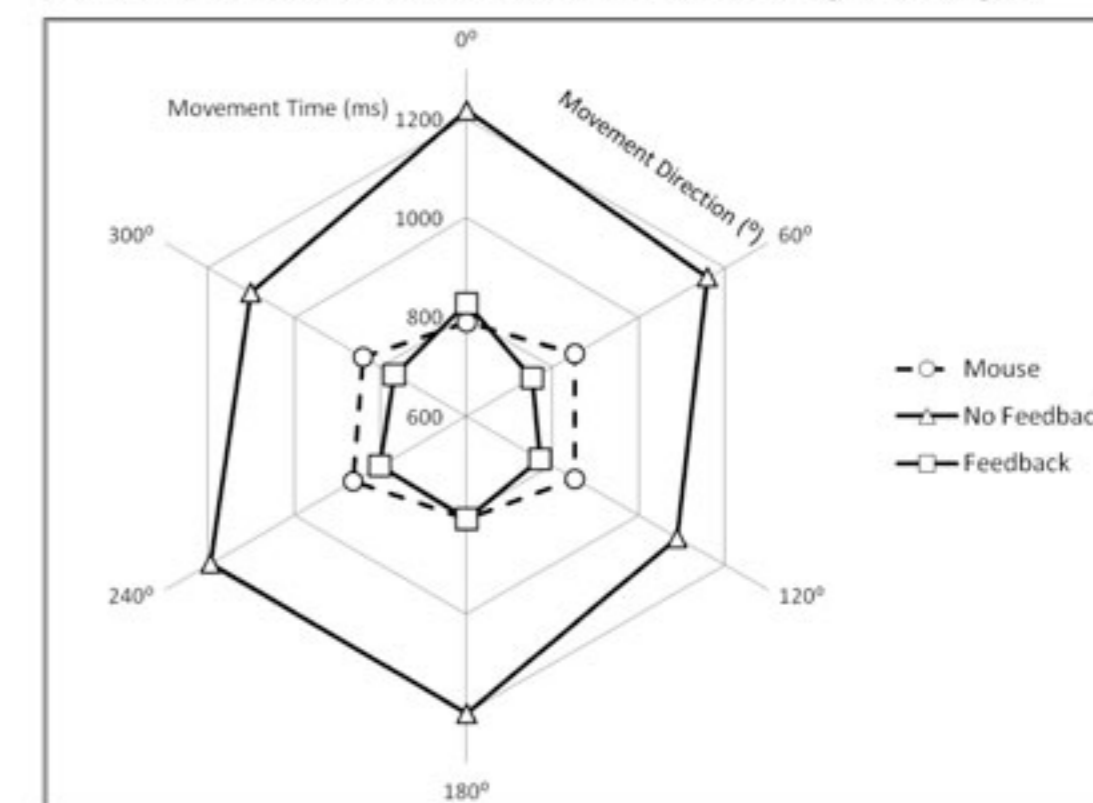
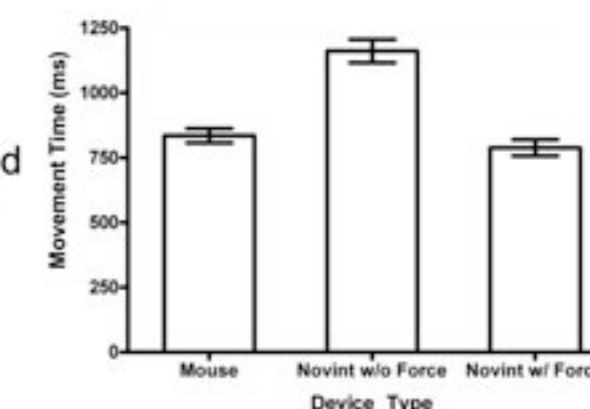


- **Target Distance:**
 - A main effect of target distance was also found, $F(1, 11) = 652.86, p < .001$
 - Significantly longer to select far target
 - Significant interaction between device type and target distance, $F(2, 22) = 20.51, p < .001$
 - Novint with Force was faster than the Mouse when participants were selecting the near target **only** ($p < .01$)



Results (cont.)

- **Device Type**
 - Main effect of device type, $F(2, 22) = 120.44, p < .001$
 - The Novint with force and Mouse conditions performed significantly faster than the Novint without Force ($p < .001$)
- **Target Angle:**
 - Significant effect of target angle, $F(5, 55) = 9.32, p < .001$
 - Significant interaction between device type and target angle, $F(10, 110) = 13.98, p < .001$
 - The Novint with Force condition resulted in significantly faster performance than the Mouse condition at diagonal angles



Conclusion

- Force-feedback led to significantly faster performance than the mouse when the demands of the task required small, fine movements (small and near targets)
 - Supports previous findings (e.g. Akamatsu and MacKenzie, 1996): force-feedback largely eliminates the need for the fine motor movements required by smaller targets and close target distances
- Force-feedback was found to produce significantly faster movements along all four diagonal axes

Proposed Future Work

- Thesis will expand on previous study with 3 main changes:
 - Multiple force values will be used (Low Force vs. High Force)
 - Goal is to determine the extent to which the level of force feedback impacts operator performance
 - There are twice as many movement directions, including movements along both the vertical and horizontal planes
 - Cursor trajectories will be recorded to analyze path of approach
- Data is currently being collected here at NASA Ames